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	Reg. No.:				103116
(680) Nesta Markes)		11- 12-1-	- 00	101	
6	uestion F	Paper Co	de: 90	401	
B.E./B.Tech. D				R/DECEME	BER 2019
(8)	Mechanica	ourth Semes Engineering	(Sandwich)		N. M
MS 8401	- INSTRUMEN	NTATION AN egulations 20		OL SYSTE	MS
Time : Three Hours				Mavimur	n : 100 Marks
ib)				waxiiiui	ii . 100 mark
	Ans	wer ALL ques	tions		
		PART – A		(10×	2=20 Marks)
1. What is calibr	eation ?				
2. Define rosette					
3. State two diff	iculties in measu	rement of higl	n resistance.		
4. List the merit	s of resistance te	mperature de	tector.		
5. What is the p	rinciple of electro	magnetic flow	meter.		
6. List any two i	mportant criteria	a to consider d	uring selecti	on a sensors	Tree
7. Why negative	feedback is inva	riably preferre	ed in a closed	loop system	n ?
8. Write the tran	nsfer function of	PID controller			
9. List the stand	lard test signal u	sed in the con	trol system.		
10. Compare DCS					
10. Compare Do.	and bonda.				
					t

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90401 PART - B (5×13=65 Marks) 11. a) i) Explain detaily any four static characteristics of instruments. ii) List the factors considered in selection of instruments. (5) (OR) b) i) Give a brief note on strain. (3) ii) With proper diagram, explain construction and orientation of strain gauge. (10)12. a) i) Explain piezo-electric instrument for acceleration measurement. (7) ii) Explain liquid in glass thermometer for temperature measurement. (6)b) With neat sketches, explain the principle, different forms of construction, resistance-temperature characteristics and applications of thermistor. (13)13. a) i) Explain any one low pressure measuring instrument. (8) ii) Short note on elastic diaphragm transducer. (5)b) Illustrate the principles, construction, different types and application of hot wire anemometer. 14. a) i) Describe important elements in the closed loop control system with example. (9) ii) Short note on multi variable control system. b) Using block diagram reduction technique find the transfer function of Y(s)/R(s) for the system given below.

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90401 -3-15. a) i) Construct Routh array and determine stability of the system represented by the characteristics equation $s^5 + s^4 + 2s^3 + 2s^2 + 3s + 5 = 0$. Command on the location of roots of characteristics equation. (7) (6) ii) Derive the response of the first order system for unit step input. b) Explain the architecture, communication facility and interface of distributed (13)control system. (1×15=15 Marks) PART - C 16. a) i) Explain construction, characteristics, applications, merits and demerits of LVDT. ii) Explain any one method for measuring very high temperature. Provide diagrams. b) i) Explain architecture, tag logging and report generation of SCADA (10)(5)ii) Short note on different types of SCADA Protocols.

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