



90175

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PART - B

(5×13=65 Marks)

11. a) Plot the following signals, given  $x[n]$  :
- i)  $x[n] = \{1, 2, 1, 2, 1, 2, 1\}$  (2)
  - ii)  $x[n-1]$  (2)
  - iii)  $x[2n]$  (2)
  - iv)  $x[n/2]$  (2)
  - v)  $x[n/2-1]$  (2)
  - vi)  $x[-n/2-1]$  (3)

(OR)

- b) Determine whether the following system is Linear, Time Invariant, Causal, Memoryless and Stable.  
 $y[n] = nx[n]$

12. a) Find the Fourier transform of the signal  $x(t) = e^{-\alpha|t|}$ ,  $\alpha > 0$  and plot its spectrum.

(OR)

- b) Specify all possible ROC's for the function  $X(s)$  given below. Also find  $x(t)$  in each case.

$$X(s) = \frac{4s}{(s+2)(s+4)}$$

13. a) Convolve the following signals  $x(t) = u(t)$   $h(t) = u(t) - u(t-2)$ .

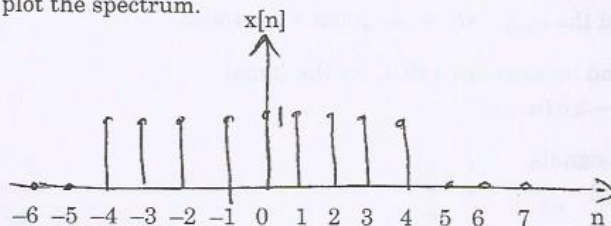
(OR)

- b) An LTI system which is initially at rest is described by the differential equation

$$\frac{d^2y}{dt^2} + 3\frac{dy}{dt} + 2y = \frac{dx}{dt} + 3x$$

Find the system function  $H(s)$  and the impulse response  $h(t)$ .

14. a) Find the DTFT of the rectangular pulse sequence shown below and also plot the spectrum.



(OR)



b) Given the z – transform of a sequence  $x[n]$  as  $X(z) = \frac{z}{z-1}$

Find the z – transform of the following signals in terms of  $X(z)$  using properties of z – transform.

- i)  $x[n-1]$  (3)
- ii)  $x[-n]$  (3)
- iii)  $\alpha^n x[n]$  (3)
- iv)  $nx[n]$  (4)

15. a) Convolve the following signals  $x[n] = \alpha^n u[n]$   $h[n] = u[n-1]$ .

(OR)

b) Consider a DT LTI system whose system function  $H(z)$  is given by

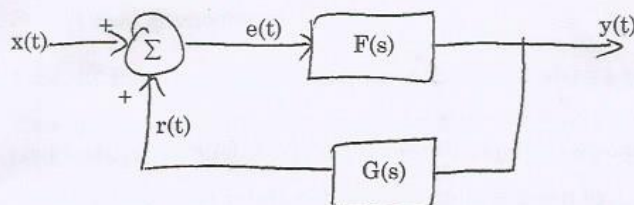
$$H(z) = \frac{z}{z-0.5} \quad |z| > 0.5.$$

Find the step response of the system.

PART – C

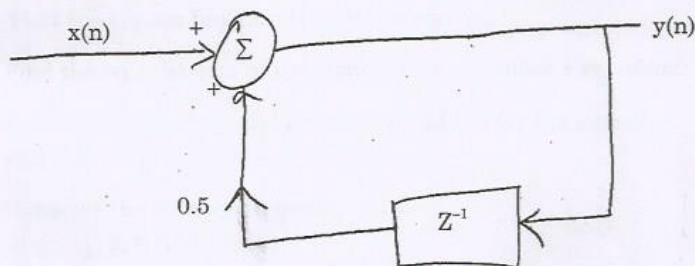
(1×15=15 Marks)

16. a) The feedback interconnection of two causal subsystems with system functions  $F(s)$  and  $G(s)$  is shown below. Find the overall system function  $H(s)$  for this feedback system.



(OR)

b) Consider the discrete time LTI system shown below.



Find the frequency response  $H(e^{j\omega})$  and the impulse response  $h(n)$  of the system. Sketch the magnitude response  $|H(e^{j\omega})|$  for the system.