

**REFERENCES:**

1. Hiriappa B, "Corporate Strategy – Managing the Business", Author House, 2013.
2. Peter F Drucker, "People and Performance", Butterworth – Heinemann [Elsevier], Oxford, 2004.
3. Vinod Kumar Garg and Venkita Krishnan N K, "Enterprise Resource Planning – Concepts", Second Edition, Prentice Hall, 2003.
4. Mark S Sanders and Ernest J McCormick, "Human Factors in Engineering and Design", McGraw Hill Education, Seventh Edition, 2013

**ME8099**

**ROBOTICS**

L	T	P	C
3	0	0	3

**OBJECTIVES:**

- To understand the functions of the basic components of a Robot.
- To study the use of various types of End of Effectors and Sensors
- To impart knowledge in Robot Kinematics and Programming
- To learn Robot safety issues and economics.

**UNIT I FUNDAMENTALS OF ROBOT**

**9**

Robot - Definition - Robot Anatomy - Co ordinate Systems, Work Envelope Types and Classification- Specifications-Pitch, Yaw, Roll, Joint Notations, Speed of Motion, Pay Load- Robot Parts and their Functions-Need for Robots-Different Applications.

**UNIT II ROBOT DRIVE SYSTEMS AND END EFFECTORS**

**9**

Pneumatic Drives-Hydraulic Drives-Mechanical Drives-Electrical Drives-D.C. Servo Motors, Stepper Motors, A.C. Servo Motors-Salient Features, Applications and Comparison of all these Drives, End Effectors-Grippers-Mechanical Grippers, Pneumatic and Hydraulic- Grippers, Magnetic Grippers, Vacuum Grippers; Two Fingered and Three Fingered Grippers; Internal Grippers and External Grippers; Selection and Design Considerations.

**UNIT III SENSORS AND MACHINE VISION**

**9**

Requirements of a sensor, Principles and Applications of the following types of sensors- Position sensors - Piezo Electric Sensor, LVDT, Resolvers, Optical Encoders, pneumatic Position Sensors, Range Sensors Triangulations Principles, Structured, Lighting Approach, Time of Flight, Range Finders, Laser Range Meters, Touch Sensors ,binary Sensors., Analog Sensors, Wrist Sensors, Compliance Sensors, Slip Sensors, Camera, Frame Grabber, Sensing and Digitizing Image Data-Signal Conversion, Image Storage, Lighting Techniques, Image Processing and Analysis-Data Reduction, Segmentation, Feature Extraction, Object Recognition, Other Algorithms, Applications-Inspection, Identification, Visual Serving and Navigation.

**UNIT IV ROBOT KINEMATICS AND ROBOT PROGRAMMING**

**9**

Forward Kinematics, Inverse Kinematics and Difference; Forward Kinematics and Reverse Kinematics of manipulators with Two, Three Degrees of Freedom (in 2 Dimension), Four Degrees of freedom (in 3 Dimension) Jacobians, Velocity and Forces-Manipulator Dynamics, Trajectory Generator, Manipulator Mechanism Design-Derivations and problems. Lead through Programming, Robot programming Languages-VAL Programming-Motion Commands, Sensor Commands, End Effector commands and simple Programs.

**UNIT V IMPLEMENTATION AND ROBOT ECONOMICS****9**

RGV, AGV; Implementation of Robots in Industries-Variou Steps; Safety Considerations for Robot Operations - Economic Analysis of Robots.

**TOTAL: 45 PERIODS****Upon the completion of this course the students will be able to**

- CO1 Explain the concepts of industrial robots, classification, specifications and coordinate systems. Also summarize the need and application of robots in different sectors.
- CO2 Illustrate the different types of robot drive systems as well as robot end effectors.
- CO3 Apply image processing techniques in robotics to improve the ability of robots.
- CO4 Develop robotic program for different tasks and familiarize with the kinematics motions of robot.
- CO5 Examine the implementation of robots in various industrial sectors and interpolate the economic analysis of robots.

**TEXT BOOKS:**

1. Groover M.P., "Industrial Robotics -Technology Programming and Applications", McGraw Hill, 2012.
2. Klafter R.D., Chmielewski T.A and Negin M., "Robotic Engineering - An Integrated Approach", Prentice Hall, 2003.

**REFERENCES:**

1. Craig J.J., "Introduction to Robotics Mechanics and Control", Pearson Education, 2008.
2. Deb S.R., "Robotics Technology and Flexible Automation" Tata McGraw Hill Book Co., 2013.
3. Fu.K.S.,Gonzalz R.C. and Lee C.S.G., "Robotics Control, Sensing, Vision and Intelligence", McGraw Hill Book Co., 1987.
4. Janakiraman P.A., "Robotics and Image Processing", Tata McGraw Hill, 1995.
5. Koren Y., "Robotics for Engineers", Mc Graw Hill Book Co., 1992.

**ME8093****COMPUTATIONAL FLUID DYNAMICS**

L	T	P	C
3	0	0	3

**OBJECTIVES:**

- To introduce Governing Equations of viscous fluid flows
- To introduce numerical modeling and its role in the field of fluid flow and heat transfer
- To enable the students to understand the various discretization methods, solution procedures and turbulence modeling.
- To create confidence to solve complex problems in the field of fluid flow and heat transfer by using high speed computers.

**UNIT I GOVERNING EQUATIONS AND BOUNDARY CONDITIONS****9**

Basics of computational fluid dynamics – Governing equations of fluid dynamics – Continuity, Momentum and Energy equations – Chemical species transport – Physical boundary conditions – Time-averaged equations for Turbulent Flow – Turbulent–Kinetic Energy Equations – Mathematical behaviour of PDEs on CFD - Elliptic, Parabolic and Hyperbolic equations.

**UNIT II FINITE DIFFERENCE AND FINITE VOLUME METHODS FOR DIFFUSION 9**

Derivation of finite difference equations – Simple Methods – General Methods for first and second order accuracy – Finite volume formulation for steady state One, Two and Three - dimensional diffusion problems –Parabolic equations – Explicit and Implicit schemes – Example problems on elliptic and parabolic equations – Use of Finite Difference and Finite Volume methods.

**UNIT III FINITE VOLUME METHOD FOR CONVECTION DIFFUSION 9**

Steady one-dimensional convection and diffusion – Central, upwind differencing schemes properties of discretization schemes – Conservativeness, Boundedness, Transportiveness, Hybrid, Power-law, QUICK Schemes.

**UNIT IV FLOW FIELD ANALYSIS 9**

Finite volume methods -Representation of the pressure gradient term and continuity equation – Staggered grid – Momentum equations – Pressure and Velocity corrections – Pressure Correction equation, SIMPLE algorithm and its variants – PISO Algorithms.

**UNIT V TURBULENCE MODELS AND MESH GENERATION 9**

Turbulence models, mixing length model, Two equation (k- $\epsilon$ ) models – High and low Reynolds number models – Structured Grid generation – Unstructured Grid generation – Mesh refinement – Adaptive mesh – Software tools.

**TOTAL: 45 PERIODS**

**OUTCOMES:**

**Upon the completion of this course the students will be able to**

- CO1 Derive the governing equations and boundary conditions for Fluid dynamics
- CO2 Analyze Finite difference and Finite volume method for Diffusion
- CO3 Analyze Finite volume method for Convective diffusion
- CO4 Analyze Flow field problems
- CO5 Explain the Turbulence models and Mesh generation techniques

**TEXT BOOKS:**

1. Ghoshdastidar, P.S., "Computer Simulation of flow and heat transfer", Tata McGraw Hill Publishing Company Ltd., 2017.
2. Versteeg, H.K., and Malalasekera, W., "An Introduction to Computational Fluid Dynamics: The finite volume Method", Pearson Education Ltd. Second Edition, 2007.

**REFERENCES:**

1. Anil W. Date "Introduction to Computational Fluid Dynamics" Cambridge University Press, 2005.
2. Chung, T.J. "Computational Fluid Dynamics", Cambridge University, Press, 2002.
3. Ghoshdastidar P.S., "Heat Transfer", Oxford University Press, 2005
4. Muralidhar, K., and Sundararajan, T., "Computational Fluid Flow and Heat Transfer", Narosa Publishing House, New Delhi, 2014.
5. Patankar, S.V. "Numerical Heat Transfer and Fluid Flow", Hemisphere Publishing Corporation, 2004

**OBJECTIVES:**

- To enable the student to understand the principles, functions and practices adapted in industry for the successful management of maintenance activities.
- To explain the different maintenance categories like Preventive maintenance, condition monitoring and repair of machine elements.
- To illustrate some of the simple instruments used for condition monitoring in industry.

**UNIT I PRINCIPLES AND PRACTICES OF MAINTENANCE PLANNING 9**

Basic Principles of maintenance planning – Objectives and principles of planned maintenance activity – Importance and benefits of sound Maintenance systems – Reliability and machine availability – MTBF, MTTR and MWT – Factors of availability – Maintenance organization – Maintenance economics.

**UNIT II MAINTENANCE POLICIES – PREVENTIVE MAINTENANCE 9**

Maintenance categories – Comparative merits of each category – Preventive maintenance, maintenance schedules, repair cycle - Principles and methods of lubrication – TPM.

**UNIT III CONDITION MONITORING 9**

Condition Monitoring – Cost comparison with and without CM – On-load testing and offload testing – Methods and instruments for CM – Temperature sensitive tapes – Pistol thermometers – wear- debris analysis

**UNIT IV REPAIR METHODS FOR BASIC MACHINE ELEMENTS 10**

Repair methods for beds, slide ways, spindles, gears, lead screws and bearings – Failure analysis – Failures and their development – Logical fault location methods – Sequential fault location.

**UNIT V REPAIR METHODS FOR MATERIAL HANDLING EQUIPMENT 8**

Repair methods for Material handling equipment - Equipment records –Job order systems -Use of computers in maintenance

**TOTAL: 45 PERIODS****OUTCOMES:**

- Upon completion of the programme, the students can able to implement the maintenance function and different practices in industries for the successful management of maintenance activities
- To identify the different maintenance categories like Preventive maintenance, condition monitoring and repair of machine elements.

**TEXT BOOKS:**

1. Srivastava S.K., "Industrial Maintenance Management", S. Chand and Co., 1981
2. Venkataraman .K "Maintenance Engineering and Management", PHI Learning, Pvt.Ltd., 2007

**REFERENCES:**

1. Armstrong, "Condition Monitoring", BSIRSA, 1988.
2. Bhattacharya S.N., "Installation, Servicing and Maintenance", S. Chand and Co., 1995
3. Davies, "Handbook of Condition Monitoring", Chapman &Hall, 1996.
4. Garg M.R., "Industrial Maintenance", S. Chand & Co., 1986.
5. Higgins L.R., "Maintenance Engineering Hand book", McGraw Hill, 5<sup>th</sup> Edition, 1988.
6. White E.N., "Maintenance Planning", I Documentation, Gower Press, 1979
7. "Advances in Plant Engineering and Management", Seminar Proceedings - IPE, 1996.

<b>ME8097</b>	<b>NON DESTRUCTIVE TESTING AND EVALUATION</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**OBJECTIVE:**

- To study and understand the various Non Destructive Evaluation and Testing methods, theory and their industrial applications.

**UNIT I OVERVIEW OF NDT 9**

NDT Versus Mechanical testing, Overview of the Non Destructive Testing Methods for the detection of manufacturing defects as well as material characterisation. Relative merits and limitations, Various physical characteristics of materials and their applications in NDT., Visual inspection – Unaided and aided.

**UNIT II SURFACE NDE METHODS 9**

Liquid Penetrant Testing - Principles, types and properties of liquid penetrants, developers, advantages and limitations of various methods, Testing Procedure, Interpretation of results. Magnetic Particle Testing- Theory of magnetism, inspection materials Magnetisation methods, Interpretation and evaluation of test indications, Principles and methods of demagnetization, Residual magnetism.

**UNIT III THERMOGRAPHY AND EDDY CURRENT TESTING (ET) 9**

Thermography- Principles, Contact and non contact inspection methods, Techniques for applying liquid crystals, Advantages and limitation - infrared radiation and infrared detectors, Instrumentations and methods, applications. Eddy Current Testing-Generation of eddy currents, Properties of eddy currents, Eddy current sensing elements, Probes, Instrumentation, Types of arrangement, Applications, advantages, Limitations, Interpretation/Evaluation.

**UNIT IV ULTRASONIC TESTING (UT) AND ACOUSTIC EMISSION (AE) 9**

Ultrasonic Testing-Principle, Transducers, transmission and pulse-echo method, straight beam and angle beam, instrumentation, data representation, A/Scan, B-scan, C-scan. Phased Array Ultrasound, Time of Flight Diffraction. Acoustic Emission Technique –Principle, AE parameters, Applications

**UNIT V RADIOGRAPHY (RT) 9**

Principle, interaction of X-Ray with matter, imaging, film and film less techniques, types and use of filters and screens, geometric factors, Inverse square, law, characteristics of films - graininess, density, speed, contrast, characteristic curves, Penetrameters, Exposure charts, Radiographic equivalence. Fluoroscopy- Xero-Radiography, Computed Radiography, Computed Tomography

**TOTAL : 45 PERIODS**

**OUTCOMES:**

**Upon the completion of this course the students will be able to**

- CO1 Explain the fundamental concepts of NDT
- CO2 Discuss the different methods of NDE
- CO3 Explain the concept of Thermography and Eddy current testing
- CO4 Explain the concept of Ultrasonic Testing and Acoustic Emission
- CO5 Explain the concept of Radiography

**TEXT BOOKS:**

- Baldev Raj, T.Jayakumar, M.Thavasimuthu “Practical Non-Destructive Testing”, Narosa Publishing House, 2014.
- Ravi Prakash, “Non-Destructive Testing Techniques”, 1st revised edition, New Age International Publishers, 2010

**REFERENCES:**

1. ASM Metals Handbook, "Non-Destructive Evaluation and Quality Control", American Society of Metals, Metals Park, Ohio, USA, 200, Volume-17.
2. ASNT, American Society for Non Destructive Testing, Columbus, Ohio, NDT Handbook, Vol. 1, Leak Testing, Vol. 2, Liquid Penetrant Testing, Vol. 3, Infrared and Thermal Testing Vol. 4, Radiographic Testing, Vol. 5, Electromagnetic Testing, Vol. 6, Acoustic Emission Testing, Vol. 7, Ultrasonic Testing
3. Charles, J. Hellier, " Handbook of Nondestructive evaluation", McGraw Hill, New York 2001.
4. Paul E Mix, "Introduction to Non-destructive testing: a training guide", Wiley, 2<sup>nd</sup> Edition New Jersey, 2005

**MS8001****TOOL DESIGN****L T P C  
3 0 0 3****OBJECTIVES:**

- To select suitable point cutting tool and multipoint cutting tool for machining process.
- Design Jigs and Fixtures for holding tool and work piece respectively.
- Use of suitable moulding for the design of die components.

**UNIT I CUTTING TOOLS****9**

Materials-properties, classification, selection, insert and coated tools, tool wear, tool life. Recent developments and applications.

**UNIT II SINGLE POINT TOOLS****9**

Nomenclature, types and styles, design and manufacture of HSS and carbide insert type tools for turning, boring, shaping, planing and slotting operations. Design of form tools. Tools and holders for CNC applications, tools for dry machining.

**MULTIPOINT CUTTERS**

Nomenclature, classification and selection, construction methods, cutter setting, design and manufacture of drills, reamers, taps, dies, thread chasers, milling cutters, broaches, hobs and gear shaper cutters. Grinding-wheel specification and selection.

**UNIT III JIGS****9**

Degrees of freedom, principles of location and clamping, principles of jig design, fool proofing, elements of jigs, classification of jigs, design of jigs for drilling and reaming.

**FIXTURES:**

Principles of fixture design, locators and different types of clamps, elements of fixtures, provision for tool setting, design of fixtures for milling, turning, boring and grinding operations. Fixtures for turning centers and machining centers. Modular fixturing-concepts and applications.

**UNIT IV PRESS TOOLS****9**

Design and manufacture of die sets for sheet metal components-simple, compound and progressive dies for punching and blanking operations. Dies for drawing and bending operations. Selection of presses and tools.

**UNIT V DESIGN OF INJECTION MOULDING AND DIE CASTING DIES****9**

Product and mould, thermal considerations, design of two plate mould, runner and gate design, mould cooling and ejection, analysis of mould flow.

SPECIAL TOOLS:

Design of limit gauges. Tool maintenance and planning.

**TOTAL : 45 PERIODS****OUTCOME:**

- Upon completion of this course the student can able to apply suitable moulding for the design of die components.

**TEXT BOOKS:**

1. Arshinov V and Alekseev G, "Metal cutting Theory and Cutting Tool Design", MIR Publishers, Moscow, 1976.
2. Donaldson C and LeCain C H, "Tool Design", Tata McGraw Hill Publishing Company Ltd., New Delhi, 2004.
3. Bhattacharyya A, "Metal Cutting Theory and Practice", New Central Books Agency (P) Ltd, Calcutta, 2000.
4. Cracknell P C and Dyson R W, "Handbook of Thermoplastics Injection Mould Design", Chapman and Hall, 1993.
5. Mikell P Groover, "Fundamentals of Modern Manufacturing", John Wiley and Sons, Singapore, 2004.

**REFERENCES:**

1. SME, "Manufacturing Engineers Hand Book", 1998.
2. Kempster, "Introduction to Jig and Tool Design", VIVA Books, New Delhi, 1998.
3. Rodin P, "Design and Production of Metal cutting Tools", MIR Publishers, Moscow, 1968.

www.AllAbtEngg.com

**GE8076****PROFESSIONAL ETHICS IN ENGINEERING****L T P C  
3 0 0 3****OBJECTIVE:**

- To enable the students to create an awareness on Engineering Ethics and Human Values to instill Moral and Social Values and Loyalty and to appreciate the rights of others.

**UNIT I HUMAN VALUES****10**

Morals, values and Ethics – Integrity – Work ethic – Service learning – Civic virtue – Respect for others – Living peacefully – Caring – Sharing – Honesty – Courage – Valuing time – Cooperation – Commitment – Empathy – Self confidence – Character – Spirituality – Introduction to Yoga and meditation for professional excellence and stress management.

**UNIT II ENGINEERING ETHICS****9**

Senses of 'Engineering Ethics' – Variety of moral issues – Types of inquiry – Moral dilemmas – Moral Autonomy – Kohlberg's theory – Gilligan's theory – Consensus and Controversy – Models of professional roles - Theories about right action – Self-interest – Customs and Religion – Uses of Ethical Theories.

**UNIT III ENGINEERING AS SOCIAL EXPERIMENTATION****9**

Engineering as Experimentation – Engineers as responsible Experimenters – Codes of Ethics – A Balanced Outlook on Law.

**UNIT IV SAFETY, RESPONSIBILITIES AND RIGHTS 9**  
 Safety and Risk – Assessment of Safety and Risk – Risk Benefit Analysis and Reducing Risk - Respect for Authority – Collective Bargaining – Confidentiality – Conflicts of Interest – Occupational Crime – Professional Rights – Employee Rights – Intellectual Property Rights (IPR) – Discrimination.

**UNIT V GLOBAL ISSUES 8**  
 Multinational Corporations – Environmental Ethics – Computer Ethics – Weapons Development – Engineers as Managers – Consulting Engineers – Engineers as Expert Witnesses and Advisors – Moral Leadership – Code of Conduct – Corporate Social Responsibility.

**TOTAL: 45 PERIODS**

**OUTCOME:**

- Upon completion of the course, the student should be able to apply ethics in society, discuss the ethical issues related to engineering and realize the responsibilities and rights in the society.

**TEXT BOOKS:**

1. Govindarajan M, Natarajan S, Senthil Kumar V. S, “Engineering Ethics”, Prentice Hall of India, New Delhi, 2004.
2. Mike W. Martin and Roland Schinzinger, “Ethics in Engineering”, Tata McGraw Hill, New Delhi, 2003.

**REFERENCES:**

1. Charles B. Fleddermann, “Engineering Ethics”, Pearson Prentice Hall, New Jersey, 2004.
2. Charles E. Harris, Michael S. Pritchard and Michael J. Rabins, “Engineering Ethics – Concepts and Cases”, Cengage Learning, 2009.
3. Edmund G Seebauer and Robert L Barry, “Fundamentals of Ethics for Scientists and Engineers”, Oxford University Press, Oxford, 2001.
4. John R Boatright, “Ethics and the Conduct of Business”, Pearson Education, New Delhi, 2003
5. Laura P. Hartman and Joe Desjardins, “Business Ethics: Decision Making for Personal Integrity and Social Responsibility” Mc Graw Hill education, India Pvt. Ltd., New Delhi, 2013.
6. World Community Service Centre, ‘ Value Education’, Vethathiri publications, Erode, 2011.

**Web sources:**

1. [www.onlineethics.org](http://www.onlineethics.org)
2. [www.nspe.org](http://www.nspe.org)
3. [www.globalethics.org](http://www.globalethics.org)
4. [www.ethics.org](http://www.ethics.org)

<b>MG8091</b>	<b>ENTREPRENEURSHIP DEVELOPMENT</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**OBJECTIVE:**

- To develop and strengthen entrepreneurial quality and motivation in students and to impart basic entrepreneurial skills and understanding to run a business efficiently and effectively.

**UNIT I ENTREPRENEURSHIP 9**  
 Entrepreneur – Types of Entrepreneurs – Difference between Entrepreneur and Intrapreneur Entrepreneurship in Economic Growth, Factors Affecting Entrepreneurial Growth.