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## ME8094 COMPUTER INTEGRATED MANUFACTURING SYSTEMS

#### **DETAILED SYLLABUS**

### **OBJECTIVE:**

• To understand the application of computers in various aspects of Manufacturing viz., Design, Proper planning, Manufacturing cost, Layout & Material Handling system.

#### **UNIT I INTRODUCTION**

Brief introduction to CAD and CAM – Manufacturing Planning, Manufacturing control-Introduction to CAD/CAM – Concurrent Engineering-CIM concepts – Computerised elements of CIM system –Types of production - Manufacturing models and Metrics – Mathematical models of Production Performance – Simple problems – Manufacturing Control – Simple Problems – Basic Elements of an Automated system – Levels of Automation – Lean Production and Just-In-Time Production.

# UNIT II PRODUCTION PLANNING AND CONTROL AND COMPUTERISED PROCESS PLANNING

Process planning – Computer Aided Process Planning (CAPP) – Logical steps in Computer Aided Process Planning – Aggregate Production Planning and the Master Production Schedule – Material Requirement planning – Capacity Planning- Control Systems-Shop Floor Control-Inventory Control – Brief on Manufacturing Resource Planning-II (MRP-II) & Enterprise Resource Planning (ERP) - Simple Problems.

### **UNIT III CELLULAR MANUFACTURING**

Group Technology (GT), Part Families – Parts Classification and coding – Simple Problems in Opitz Part Coding system – Production flow Analysis – Cellular Manufacturing – Composite part concept – Machine cell design and layout – Quantitative analysis in Cellular Manufacturing – Rank Order Clustering Method - Arranging Machines in a GT cell – Hollier Method – Simple Problems.

# UNIT IV FLEXIBLE MANUFACTURING SYSTEM (FMS) AND AUTOMATED GUIDED VEHICLE SYSTEM (AGVS)

Types of Flexibility - FMS – FMS Components – FMS Application & Benefits – FMS Planning and Control – Quantitative analysis in FMS – Simple Problems. Automated Guided Vehicle System (AGVS) – AGVS Application – Vehicle Guidance technology – Vehicle Management & Safety.

## **UNIT V INDUSTRIAL ROBOTICS**

Robot Anatomy and Related Attributes – Classification of Robots- Robot Control systems – End Effectors – Sensors in Robotics – Robot Accuracy and Repeatability - Industrial Robot Applications – Robot Part Programming – Robot Accuracy and Repeatability – Simple Problems.

### Diploma, Anna Univ UG & PG Courses

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## **TEXT BOOKS:**

- 1. Mikell. P. Groover "Automation, Production Systems and Computer Integrated Manufacturing", Prentice Hall of India, 2008.
- 2. Radhakrishnan P, Subramanyan S. and Raju V., "CAD/CAM/CIM", 2nd Edition, New Age International (P) Ltd, New Delhi, 2000.

### **REFERENCES:**

- 1. Gideon Halevi and Roland Weill, "Principles of Process Planning A Logical Approach" Chapman & Hall, London, 1995.
- 2. Kant Vajpayee S, "Principles of Computer Integrated Manufacturing", Prentice Hall India.
- 3. Rao. P, N Tewari &T.K. Kundra, "Computer Aided Manufacturing", Tata McGraw Hill Publishing Company, 2000.