

OBJECTIVES:

- To introduce the components and their representation of control systems
- To learn various methods for analyzing the time response, frequency response and stability of the systems.
- To learn the various approach for the state variable analysis.

UNIT I SYSTEMS COMPONENTS AND THEIR REPRESENTATION 9

Control System: Terminology and Basic Structure-Feed forward and Feedback control theory
Electrical and Mechanical Transfer Function Models-Block diagram Models-Signal flow graphs
models-DC and AC servo Systems-Synchronous -Multivariable control system

UNIT II TIME RESPONSE ANALYSIS 9

Transient response-steady state response-Measures of performance of the standard first order and second order system-effect on an additional zero and an additional pole-steady error constant and system- type number-PID control-Analytical design for PD, PI, PID control systems

UNIT III FREQUENCY RESPONSE AND SYSTEM ANALYSIS 9

Closed loop frequency response-Performance specification in frequency domain-Frequency response of standard second order system- Bode Plot - Polar Plot- Nyquist plots-Design of compensators using Bode Plots-Cascade lead compensation-Cascade lag compensation-Cascade lag-lead compensation

UNIT IV CONCEPTS OF STABILITY ANALYSIS 9

Concept of stability-Bounded - Input Bounded - Output stability-Routh stability criterion-Relative Stability-Root locus concept-Guidelines for sketching root locus-Nyquist stability criterion.

UNIT V CONTROL SYSTEM ANALYSIS USING STATE VARIABLE METHODS 9

State variable representation-Conversion of state variable models to transfer functions-Conversion of transfer functions to state variable models-Solution of state equations-Concepts of Controllability and Observability-Stability of linear systems-Equivalence between transfer function and state variable representations-State variable analysis of digital control system-Digital control design using state feedback.

TEXT BOOK:

1. M. Gopal, —Control System – Principles and Design, Tata McGraw Hill, 4th Edition, 2012.

REFERENCES:

1. J. Nagrath and M. Gopal, —Control System Engineering, New Age International Publishers, 5th Edition, 2007.
2. K. Ogata, 'Modern Control Engineering', 5th edition, PHI, 2012.