

DETAILED SYLLABUS

UNIT I STATICS OF PARTICLES

Introduction – Units and Dimensions – Laws of Mechanics – Lami's theorem, Parallelogram and triangular Law of forces – Vectorial representation of forces – Vector operations of forces - additions, subtraction, dot product, cross product – Coplanar Forces – rectangular components – Equilibrium of a particle – Forces in space – Equilibrium of a particle in space – Equivalent systems of forces – Principle of transmissibility.

UNIT II EQUILIBRIUM OF RIGID BODIES

Free body diagram – Types of supports – Action and reaction forces – stable equilibrium – Moments and Couples – Moment of a force about a point and about an axis – Vectorial representation of moments and couples – Scalar components of a moment – Varignon's theorem – Single equivalent force -Equilibrium of Rigid bodies in two dimensions – Equilibrium of Rigid bodies in three dimensions

UNIT III PROPERTIES OF SURFACES AND SOLIDS

Centroids and centre of mass – Centroids of lines and areas - Rectangular, circular, triangular areas by integration – T section, I section, - Angle section, Hollow section by using standard formula – Theorems of Pappus - Area moments of inertia of plane areas – Rectangular, circular, triangular areas by integration – T section, I section, Angle section, Hollow section by using standard formula – Parallel axis theorem and perpendicular axis theorem – Principal moments of inertia of plane areas – Principal axes of inertia-Mass moment of inertia – mass moment of inertia for prismatic, cylindrical and spherical solids from first principle – Relation to area moments of inertia.

UNIT IV DYNAMICS OF PARTICLES

Displacements, Velocity and acceleration, their relationship – Relative motion – Curvilinear motion - Newton's laws of motion – Work Energy Equation– Impulse and Momentum – Impact of elastic bodies.

UNIT V FRICTION AND RIGID BODY DYNAMICS

Friction force – Laws of sliding friction – equilibrium analysis of simple systems with sliding friction – wedge friction-. Rolling resistance -Translation and Rotation of Rigid Bodies – Velocity and acceleration – General Plane motion of simple rigid bodies such as cylinder, disc/wheel and sphere.

TEXT BOOKS:

1. Beer, F.P and Johnston Jr. E.R., "Vector Mechanics for Engineers (In SI Units): Statics and Dynamics", 8th Edition, Tata McGraw-Hill Publishing company, New Delhi (2004).
2. Vela Murali, "Engineering Mechanics", Oxford University Press (2010)

OBJECTIVES:

- To develop capacity to predict the effect of force and motion in the course of carrying out the design functions of engineering.